

Importance Function Derivation for RESTART Simulations of Petri Nets

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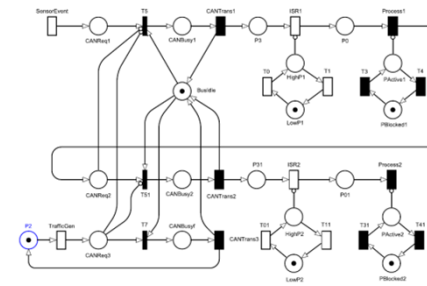
Outline

- Stochastic Petri Nets
- RESTART Simulation
- A-Priori Estimation of Rare Event Frequencies
- A Heuristic Importance Function for SPNs
- An Example
- Conclusion

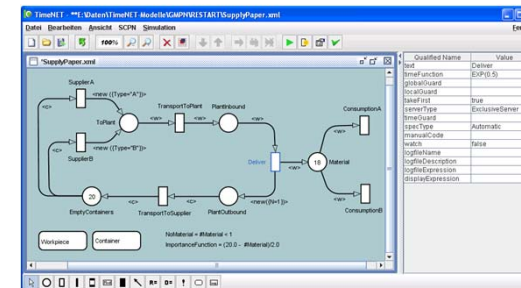
Introduction

▪ Accessible Rare-Event Simulation

- ▶ Underlying model
 - Stochastic Petri nets



- ▶ Software Tool
 - TimeNET



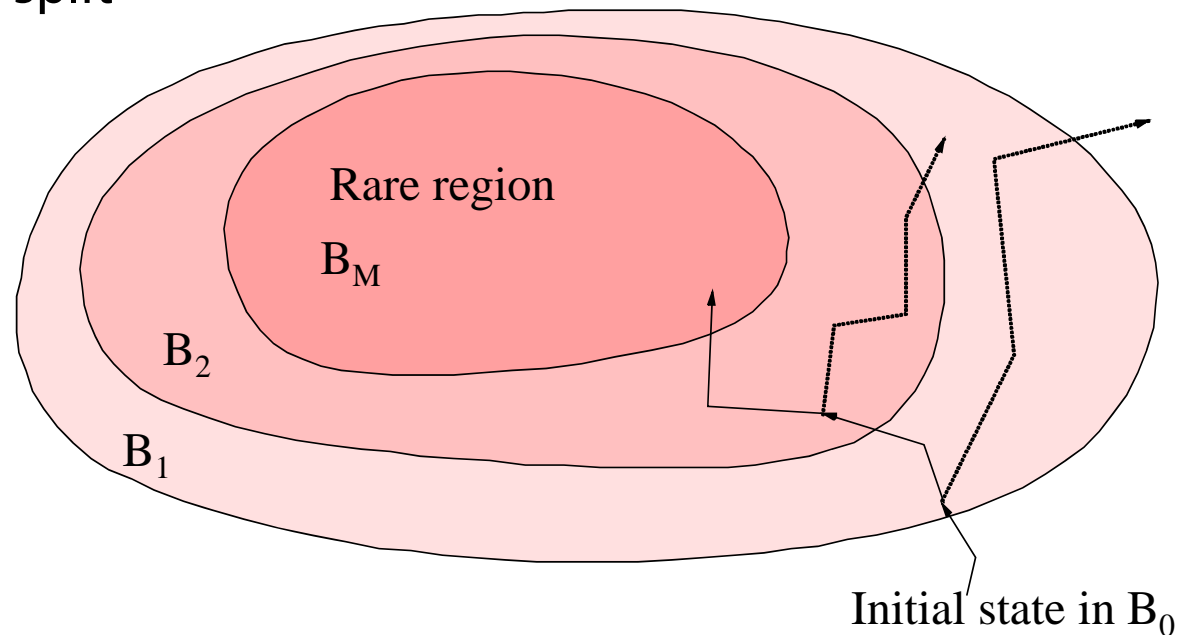
- ▶ **Less** expert knowledge
 - Semi-automatic parameter setting

RESTART

▪ Splitting Simulation

- ▶ Model and simulation loop as (semi-) black box
- ▶ Controlling RESTART algorithm only needs to ...
 - Store and recall state
 - Decide when to split and how often

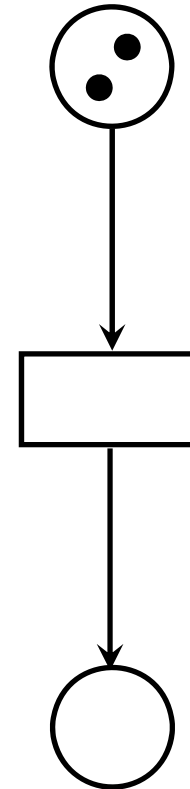
- Technical:
Importance function
and **Levels**
- Crucial for speedup!



Stochastic Petri Nets

▪ Model Elements

- ▶ **Places** P – state variables
 - Marking – state, initial: \mathbf{m}_0
- ▶ **Transitions** T – events
 - Input arcs $\mathbf{Pre} : P \times T \rightarrow \mathbb{N}$
 - Arc multiplicities
 - Enabling and firing
- ▶ **Performance measures**
 - Rate and impulse rewards
 - Concentrate on rare transition t_{rare} firing frequency γ



Stochastic Petri Nets

▪ Algebraic Description

▶ **Marking** vector $\mathbf{m} \in \mathbb{N}^{|P|}$ and direct reachability $\mathbf{m} \xrightarrow{t} \mathbf{m}'$

▶ **Incidence matrix** \mathbf{C} with dimensions $|P| \times |T|$
 $\mathbf{C}(p, t)$ denotes token change in p when t is fired

▶ **Next marking** $\mathbf{m}' = \mathbf{m} + \mathbf{C} \cdot (0, \dots, 0, 1_t, 0, \dots, 0)$

▶ **State equation** $\mathbf{m} = \mathbf{m}_0 + \mathbf{C} \sigma$
for a firing count vector $\sigma \in \mathbb{N}^{|T|}$

▶ **Invariants** (P- and T-semiflows)

$$\mathbf{y} \mathbf{C} = 0 \quad \longrightarrow \quad \mathbf{y} \mathbf{m} = \mathbf{y} \mathbf{m}_0 + \mathbf{y} \mathbf{C} \sigma = \mathbf{y} \mathbf{m}_0 = \text{const.}$$

$$\mathbf{C} \mathbf{x} = 0 \quad \longrightarrow \quad \mathbf{m}' = \mathbf{m} + \mathbf{C} \mathbf{x} = \mathbf{m}$$

A-Priori Estimation

▪ Estimation of Performance Measures

- ▶ [Campos et. al.]
- ▶ Structural analysis of model
 - ⇒ constraints for upper and lower bounds of results
- ▶ Based on incidence matrix and other model information
- ▶ Formulation as a linear programming problem

- ▶ Notation: firing frequency = throughput
= inverse of average interfering time

$$\gamma = \chi[t_{rare}] = \frac{1}{\Gamma[t_{rare}]}$$

A-Priori Estimation

▪ Visit Ratios and Service Demands

- ▶ Derive **relative visit ratios** $\mathbf{v}^{(1)} : T \rightarrow \mathbb{R}^+$ of transitions using incidence matrix, transition invariants, and firing probabilities of conflicting transitions, relative to t_{rare}
- ▶ Define **average service demands** $\overline{\mathbf{D}}^{(1)} : T \rightarrow \mathbb{R}^+$ relative to a transition by multiplying visit ratios by a transition's mean service time $\overline{s}[t_i]$ (its delay)

$$\overline{\mathbf{D}}^{(1)}[t_i] = \mathbf{v}^{(1)}[t_i] \overline{s}[t_i]$$

A-Priori Estimation

▪ LPP Formulation for Bounds

- ▶ Apply **Little's Law** to each (timed) transition and its input places for ($\bar{\mathbf{m}}$ denotes the mean marking vector)

$$\Gamma[t_{rare}] \bar{\mathbf{m}} \geq \mathbf{Pre} \cdot \bar{\mathbf{D}}^{(1)}$$

- ▶ and thus

$$\Gamma[t_1] \geq \max_{\mathbf{y} \in \{\text{P-semiflows}\}} \frac{\mathbf{y} \cdot \mathbf{Pre} \cdot \bar{\mathbf{D}}^{(1)}}{\mathbf{y} \cdot \mathbf{m}_0}$$

- ▶ Leading to a **bound** for the **mean interfering time**

$$\begin{array}{ll} \Gamma[t_{rare}] = & \text{maximum} \\ & \mathbf{y} \cdot \mathbf{Pre} \cdot \bar{\mathbf{D}}^{(1)} \\ & \text{subject to} \\ & \mathbf{y} \cdot \mathbf{C} = 0 \\ & \mathbf{y} \cdot \mathbf{m}_0 = 1 \\ & \mathbf{y} \geq 0 \end{array}$$

A-Priori Estimation

- **Throughput Estimation**

- ▶ **Throughput upper bound**

$$\chi_+[t_{rare}] = \frac{1}{\Gamma[t_{rare}]}$$

- ▶ **Throughput lower bounds:** worst-case interfering time after all other transitions have fired using visit ratios

$$\chi_-[t_1] = \frac{1}{\sum_{t \in T} \bar{\mathbf{D}}^{(1)}[t]}$$

$$\chi_-[t_j] = \chi_-[t_1] \mathbf{v}^{(1)}[t_j]$$

- ▶ **Heuristic estimate:** weighted average of bounds

$$\gamma = \chi[t_{rare}] \approx \alpha \chi_-[t_{rare}] + (1 - \alpha) \chi_+[t_{rare}]$$

Heuristic Importance Function

▪ State Distances in Petri Nets

- ▶ Following similar ideas, the minimal number of events (transition firings) $h(\mathbf{m}, t_{rare})$ to reach a marking \mathbf{m}' enabling transition t_{rare} is

$$\begin{array}{llll} \text{minimize} & h(\mathbf{m}, t_{rare}) & = & \mathbf{x} \mathbf{1} \\ \text{subject to} & \mathbf{m}' & = & \mathbf{m}_0 + \mathbf{C} \mathbf{x} \\ & \mathbf{x} & \geq & 0 \\ & \mathbf{m}' & \geq & \mathbf{Pre}(\cdot, t_{rare}) \end{array}$$

- ▶ **Admissible** and **monotone** \Rightarrow useful for search problems
- ▶ Can be generalized to general marking conditions

Heuristic Importance Function

▪ Importance Function Definition

- ▶ Let $h_{\max} = h(\mathbf{m}_0, t_{rare})$, the maximum* state distance
- ▶ **Importance function** for marking \mathbf{m} :

$$f_I(\mathbf{m}) = h_{\max} - h(\mathbf{m}, t_{rare})$$

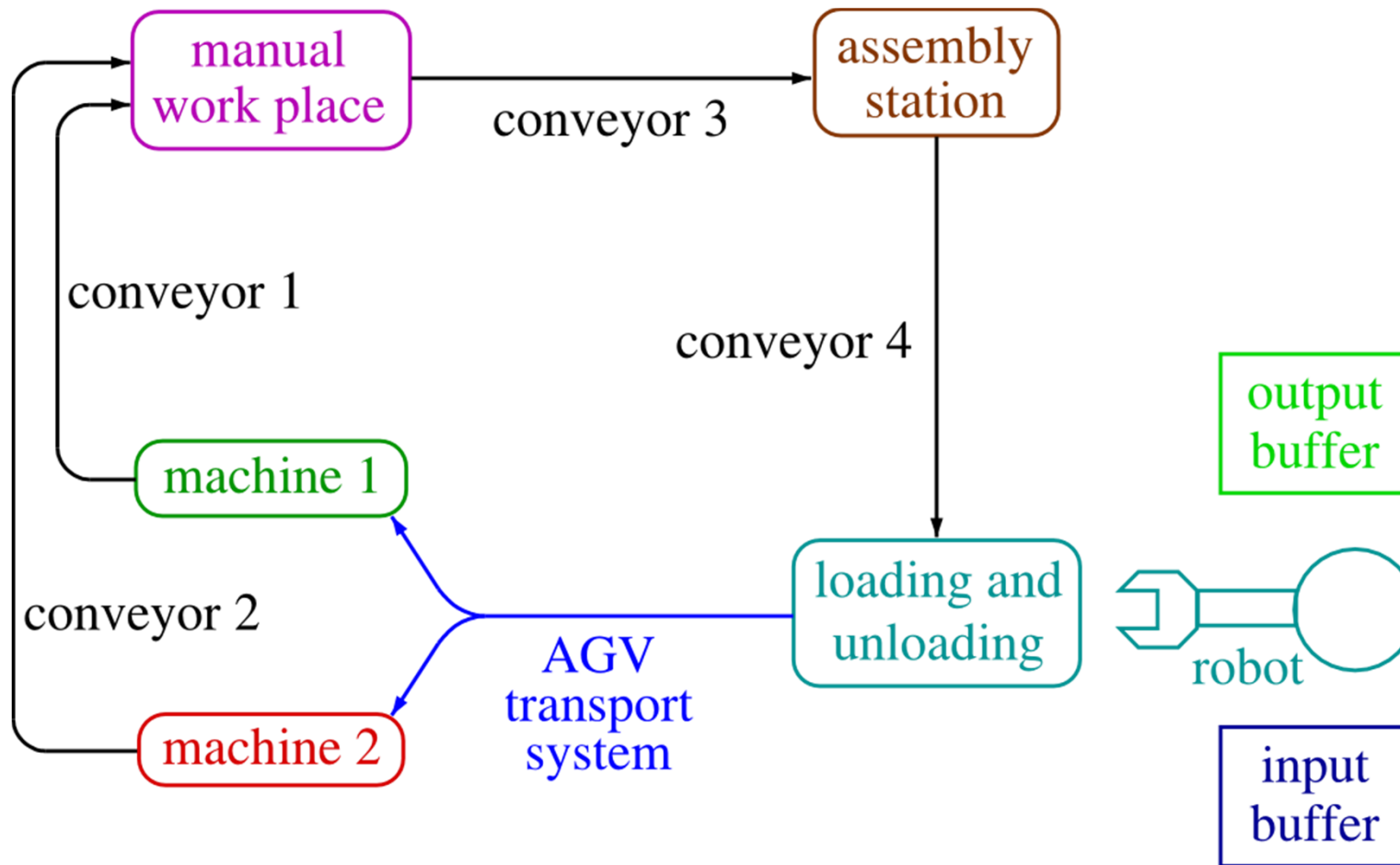
- ▶ #Levels, optimal: $L_{\text{opt}} = \frac{\ln \gamma}{\ln p_k}$ with $p_k \in [\frac{1}{2}, e^{-2}]$

maximum: $L = \min(L_{\text{opt}}, h_{\max})$

- ▶ **Threshold setting:** $Thr_i = \left\lfloor i \frac{h_{\max}}{L} \right\rfloor$

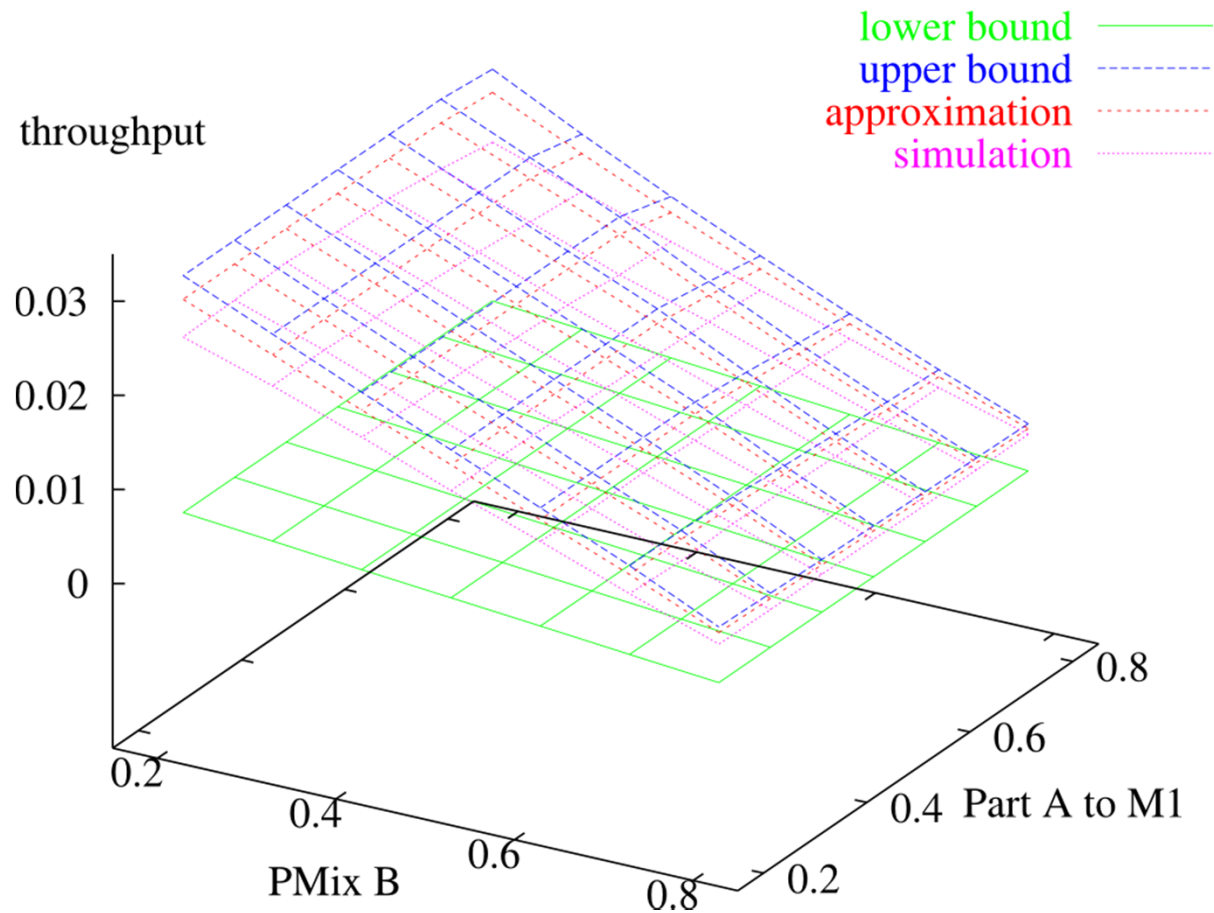
Example

Flexible Manufacturing System



Example

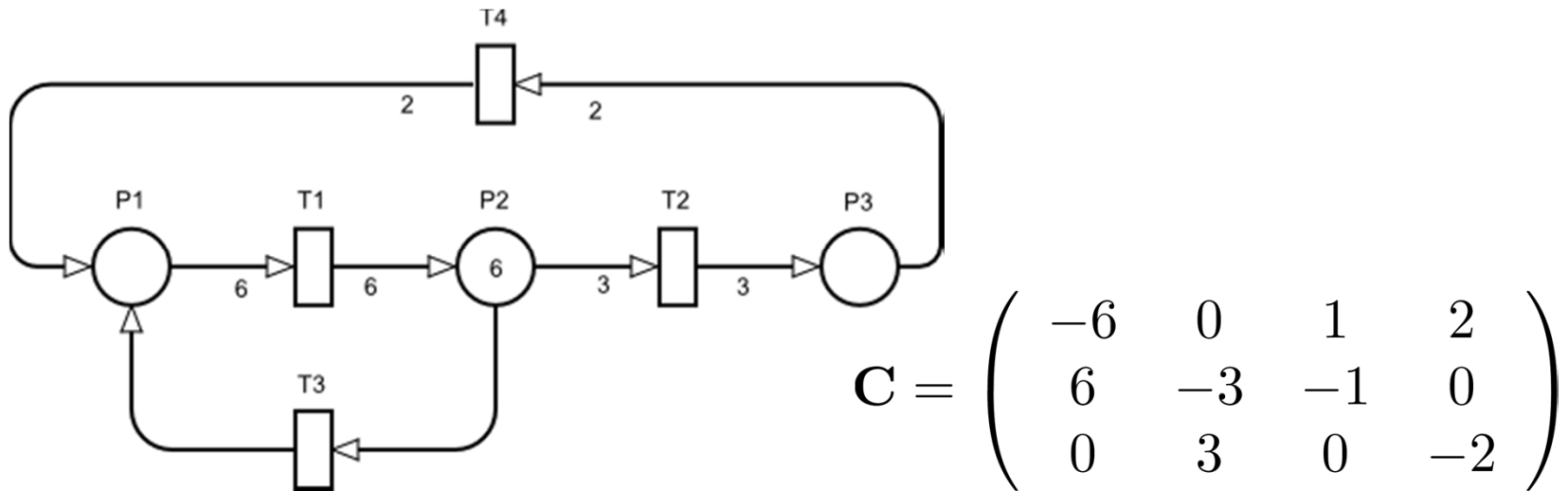
▪ Throughput Estimation Quality



Example

- **State Distance Heuristic**

- ▶ Simple model (manual solution)



- ▶ How many transition firings until T1 is enabled?

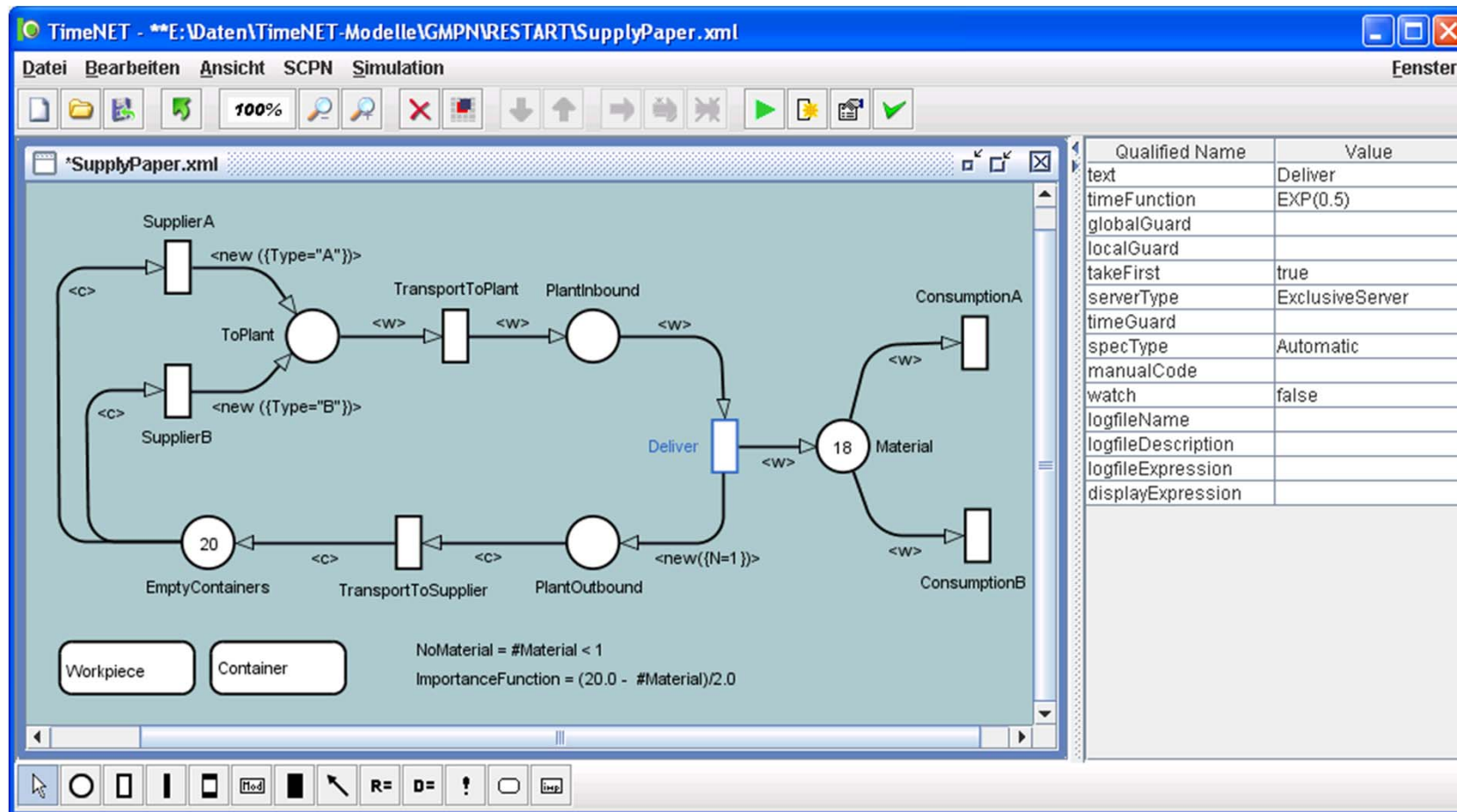
5: 2x T2, 3x T4

(if arc multiplicities of T2 or T4 are decreased, then 6x T3)

Conclusion

- **Improvement of RESTART usability for SPNs**
 - ▶ A-priori estimation of rare event frequency
 - ⇒ **Optimal number of thresholds**
 - ▶ Heuristic state distance measure
 - ⇒ **Importance function**
- **Open Issues**
 - ▶ Estimate other types of performance measures
 - ▶ Guidance quality of state distance heuristic
 - ▶ Tool implementation and complex examples
 - ▶ Computational effort?

Tool TimeNET



Stochastic Petri net tool – available at www.tu-ilmenau.de/sse/TimeNET